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Bridging Mathemdtical Programming-Based Two-Group Classification with Bayes Decision Approach
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\section*{I. Introduction}

Over the years a considerable amount of literature has been accumulated on classification (discriminant analysis), in various fields, including engineering, medical and social sciences, biology, economics, marketing, finance and management (McLachlan, 1992; Ragsdale and Stam, 1992) .

The best developed and earliest [15, 16, 25] and appeared [12, 37, 38, 40] was the statistical theory of classification. We will refer to it as a traditional classification theory. This theory is based on the Bayes decision approach [4, 10] that seeks to divide the space of observations into mutually exclusive and exhaustive regions such that if one doservation falls into the \(i\)-th region it will be allocated to \(i\)-th class (group). The classification regions are defined by minimization of the expected costs due to a wrong decision.

The research conducted over the past twenty years was aimed at the development and/or application of different mathematical approaches for classification, such as: mathematical programming ( MP ) - based classification [34], neural networks (NN) [24, 29], support vector (SV) learning [32, 36], genetic algorithms (GA) [9, 14]. We will call all these approaches nontraditional classification approaches.

The main reason for the development of a such tremendous variety of classification procedures (classifiers) is that no superior classifier can be found among them. The usual practice for a particular application is to try as many as possible classifiers in order to choose the best one. Unfortunately, the most of the researchers and users in the field of classification use very restricted number of classifiers - the scientists working in the field of statistical classification use mainly statistical classifiers while the scientists from nontraditional classification fields use mainly classifiers from their own field and some well known (linear - LDF and quadratic - QDF discriminant function, logistic discrimination - \(L D\), nearest neighbors - \(k \mathbb{N N}\) ) statistical classifiers. Rarely [18, 26, 28] papers on statistical discriminant analysis include comparison with nontraditional classifiers (MP, NN, SV) .

How could be explained this lack of serious interest by statisticians, working in the field of classical classification, regarding the nontraditional (e.g. MP, NN, SV, GA) classification approaches? In our opinion the main reason for that is the non Bayes decision theoretical approach basis of the most of the nontraditional classification approaches.

The most popular classifiers are the linear ones. They could be constructed using different classification approaches: statistical \([3,12,13,18,25]\), qeerational research [ 5,39 ], mathematical programming [ \(5,11,30\) ], genetic algorithms [9], support vector [32] and other approaches. In this paper we will show that any linear classifier could be considered within the Bayes decision theoretic approach framework. We will carry out our consideration about the mixed integer programming based linear classifier since this is the only classifier that directly minimizes the number of misclassifications and it is the best classifier if the criterion is minimum error rate on the training set. However we would like to stress again that our consideration is valid for any linear classifier.

\section*{II. Mathematical programming based classification}

During the last twenty years, a class of non-parametric mathematical programming (MP) -based techniques has attracted considerable research attention [33]. We will focus our attention to the mixed-integer programming (MIP) classification approach since only it minimizes directly the number of misclassifications while all statistical procedures minimize this number indirectly by minimizing the value of the misclassification probability. There are several studies devoted to MIP classification algorithms (e.g. [11, 21, 31]). Unfortunately all known MIP-based classification formulations are NP -hard [2] and there is no hope to obtain fast (polynomial time) algorithms for their solving unless \(P=N P\).

A number of studies compared the MIP classification method with the most frequently used statistical methods (LDF, QDF, ID) using either real or simulated data \([1,6,8,20,21,23,30,34,35]\). The conclusions of these studies are not unifomly supportive of the MIP classification method but there is a fair amount of support for the statement that it has classified sunprisingly well if the data are highly skewed or outlier-contaminated. Very often it clearly outperforms the above mentioned statistical discriminant methods.

The well known \(\mathbb{M P}\) formulations are based on the geometrical point of view in respect to the discrimination. They construct hyperplane by minimization of some criterion, based on the values proportional to the Euclidean distances of the points to the hiperplane taking into account their position relative to it. Such an approach belongs to the distance-based discrimination. There are a lot of distance measures, proposed for discriminant purposes. Most of these measures have a probability interpretation (they use the probability density functions, covariance matrix etc.) and their application for discriminant punposes is based on the Bayes decision-theoretic approach. The Euclidean distance (this is the Mahalanobis distance in casde of independent variables) has a geometrical sense, but not the probability one. Such an approach is not a Bayes decision-making approach. It seems that this non-Bayes approach is one of explanations for the lack of serious interest of the statisticians in MP classification.

The purpose of this paper is to show the connection between the Bayes decisiontheoretic approach and MIP-based classification. In Section 3 we consider the classical two-group MIP-based formulation of linear classifier's construction. Section 4 is dedicated on the non-parametric estimation of the multivariate normal distribution parameters based on the minimization of the divergence criterion.

\section*{III. MIP-based classification}

Let us consider the classical sample-based two-group classification problem: \(g_{1}\) and \(g_{2}\) are two distinct groups with prior probabilities \(q_{1}\) and \(q_{2}\left(q_{1}+q_{2}=1\right)\); a training set of \(n=n_{1}+n_{2}\) samples ( \(n_{1}\) from \(g_{1}\) and \(n_{2}\) from \(g_{2}\) ) is available described by a \(k\)-component vector of variables \(\mathbf{x}^{T}=\left(x_{1}, \ldots, x_{k}\right)\). The aim of the discriminant analysis is build a decision function \(f(\boldsymbol{w}, \mathbf{x})\) such that \(\mathbf{x} \in g_{1}\) if \(f(\boldsymbol{w}, \mathbf{x}) \geq w_{0}\), otherwise \(\mathbf{x} \in g_{2}\); \(\mathbf{w}=\left(w_{1}, \ldots, w_{k}\right)^{\mathrm{T}}\) is a vector of the classifier's parameters and \(w_{0}\) is a cutoff value. The most frequently used decision function \(f(\boldsymbol{w}, \mathbf{x})=\boldsymbol{w} \mathbf{x}-w_{0}\) is linear (this is a hyperplane in the \(k\)-dimensional attribute space).

The conventional MIP-formulation of the linear classifier's construction is as follows:
(1)
\[
\text { minimize } \quad z=\sum_{x_{1} \in g_{1} n_{1}}^{q_{1}}\left|i y_{i}+\sum_{x_{1} \in g_{2}}^{q_{2}} \dot{n}_{2}\right| y_{i}
\]
subject to
(2)
\[
\begin{aligned}
& x_{i}^{\mathrm{T}} W+M y_{i} i W_{0}, \text { if } x_{i} \in g_{1}, \\
& x_{i}^{\mathrm{T}} W+M y_{i}<W_{0}, \text { if } x_{i} \in g_{1}
\end{aligned}
\]
where \(W_{j}(j=0,1, \ldots, k)\) are unrestricted (they correspond to the coefficients of the decision hyperplane) ; the 0/1 integer variable \(y_{i}\) is equal to 1 if the \(i\)-th doservation is misclassified, and \(y_{i}\) is equal to 0 otherwise (correct classification), \(i=1, \ldots, n ; M\) is a sufficiently large positive real number. Obviously the objective function \(z\) is equal to the overall misclassification error. This is a problem of the discrete optimization and in general case there is not a unique optimal solution.

Definition. Two optimal solutions of the MP-based classification problem (1)- (2) will differ from classification point of view if and only if their linear classification functions assign at least one sample to different groups.

Let \(\mathrm{OS}_{1}\) and \(\mathrm{OS}_{2}\) are two optimal solutions of the MIP-based classification problem (1)-(2). Therefore they have one and the same minimal value of the object function (1) and they differ at least in one value of the classification function's parameters \(w_{j}, j=0,1, \ldots, k\). These two optimal solutions differ from classification point of view if there exists at least one sample, such that if \(\mathrm{OS}_{1}\) assigns it to say \(g_{1}\) then \(\mathrm{OS}_{2}\) assigns it to \(g_{2}\) (or viœe versa). The number of the optimal solutions is finite since the training sample set is finite. Let \(\mathbf{v}=\left(v_{1}, \ldots, v_{k}\right)^{\mathrm{T}}\) and \(v_{0}\) are the parameter values of the optimal solution OS. These values allow us to assign every observation from the training set to one of the two groups, or in other words we have the following consistent system from \(n\) inequalities:
\[
\left.x_{i}^{\mathrm{T}} W i w_{0}, \text { if OS assigns } x_{i} \text { into } g_{1} \text { (obviously it is possible } x_{i} \notin g_{1}\right)
\]
\(x_{i}^{T} W<w_{0}\), if OS assigns \(x_{i}\) into \(g_{2}\) (obviously it is possible \(x_{i} \notin g_{2}\) ),
and \(\operatorname{OS}\left(w_{j}=v_{j}, j=0,1, \ldots, k\right)\) is a possible solution of the system (3) . Obviously every optimal solution OS from classification point of view is a set of infinite number of optimal solutions from mathematical point of view that differ in some values of the classification function parameters ( \(w_{j}, j=0,1, \ldots, k\) ), but all these solutions assign each training set observation to one and the same group.
IV. Estimation of the parameters of the multivariate nomal distribution based on MIP classification and divergence criterion

We will consider a particular optimal (from classification point of view) solution OS of the classification problem.

Let us accept that the both groups have multivariate normal distribution with common covariance matrix \(-\boldsymbol{N}\left(\mu_{i}, \Sigma\right), i=1,2\). We look for such estimations of the
means \(\tilde{\mu}_{i}, i=1,2\) and the covariance matrix \(\tilde{\Sigma}\) so that:
a) following the Bayes approach (with \(\boldsymbol{N}\left(\tilde{\mu}_{i}, \tilde{\Sigma}, i=1,2\right)\) the same assignment of the samples from the training set will be obtained as with the OS (see (3));
b) the divergence criterion between the multivariate normal distributions \(\boldsymbol{N}\left(\widetilde{\mu}_{i}, \tilde{\Sigma}\right.\) and \(\boldsymbol{N}\left(\hat{\mu}_{i}, \hat{\Sigma}\right), i=1,2\), has to be minimum, where \(\hat{\mu}_{i}, i=1,2\), and \(\hat{\Sigma}\) are the maximum-likelihood estimations of the means and the covariance matrix.

This is a typical qptimization task. First of all let us consider the criterion that should be minimized. The divergence between the multivariate normal distributions \(\boldsymbol{N}\left(\tilde{\mu}_{i}, \tilde{\Sigma}\right.\) and \(\boldsymbol{N}\left(\hat{\mu}_{i}, \hat{\Sigma}\right)\) with density functions \(\tilde{p}\left(x / g_{i}\right)\) and \(\hat{p}\left(x / g_{i}\right)\) is as follows [22]:
(4)

Therefore we should minimize the following criterion:
(5) \(\quad Q=\sum_{i=1}^{2} n_{i} D\left(\boldsymbol{N}\left(\tilde{\mu}_{i}, \tilde{\Sigma} \| \boldsymbol{N}\left(\hat{\mu}_{i}, \hat{\Sigma}\right)\right)\right.\).

Now let us consider the conditions under which the criterion should be minimized.

The class of the optimal (Bayes) classification rules for groups with multivariate normal distribution with cormon covariance matrix is based on the linear discriminant function (LDF - see [4]) :
(6) \(\quad f_{i}(x)=w_{i}^{\mathrm{T}} x+w_{i 0}, \quad w_{i}=\tilde{\Sigma}^{-1} \widetilde{\mu}_{i}, w_{i 0}=-\int_{2}^{1} \tilde{\mu}_{i}^{\mathrm{T}} \tilde{\Sigma}^{\mathrm{T}} \widetilde{\mu}_{i}+\ln \left(q_{i}\right), i=1,2\).

Then the linear classifier has the form: \(x \in g_{1}\) if \(f(w, x)=w^{\top} x \geq w_{0}\) otherwise \(\mathbf{x} \in g_{2}\), where:
(7) \(w=w_{1}-w_{2}=\tilde{\Sigma}^{1}\left(\tilde{\mu}_{1}-\tilde{\mu}_{2}\right)\),

Let us now summarize the optimization problem:
(9) \(\quad Q=n[\ln (|\hat{\Sigma}|)-\ln (|\tilde{\Sigma}|)+\operatorname{tr}(\widetilde{\Sigma} \hat{\Sigma}-I)]+n_{1}\left(\widetilde{\mu}_{1}-\hat{\mu}_{1} T^{T} \hat{\Sigma}^{-1}\left(\widetilde{\mu}_{1}-\hat{\mu}_{1}\right)+\right.\)
\[
+n_{2}\left(\tilde{\mu}_{2}-\hat{\mu}_{2}\right)^{t} \hat{\Sigma}^{-1}\left(\tilde{\mu}_{2}-\hat{\mu}_{2}\right)
\]
subject to:
\[
\begin{align*}
& x_{i}^{\mathrm{T}} W \text { i } w_{0}, \text { if } O S \text { assigns } x_{i} \text { into } g_{1} \\
& x_{i}^{\mathrm{T}} W<w_{0}, \text { if } O S \text { assigns } x_{i} \text { into } g_{2}  \tag{10}\\
& w=\tilde{\Sigma}^{-1}\left(\tilde{\mu}_{1}-\tilde{\mu}_{2}\right)
\end{align*}
\]
(12)
\[
w_{0}={ }_{2}^{1}\left(\begin{array}{c}
1 \\
1
\end{array}\left(\tilde{\mu}_{1}+\tilde{\mu}_{2}\right)^{\mathrm{T}} w+\ln \left(\begin{array}{c}
q_{1} \\
1 \\
q_{1}
\end{array}\right) .\right.
\]
where \(w_{0}\) and the components of \(w, \tilde{\mu}_{1}, \tilde{\mu}_{2}\), and \(\tilde{\sum}\) are unrestricted; \(q_{1}, q_{2}\) and all elements of \(\hat{\mu}_{1}, \hat{\mu}_{2}\), and \(\hat{\Sigma}\) are real constants.

The considered optimization problem is too complicated and we should simplify土
IV.1. \(\widetilde{\mu}_{1}=\hat{\mu}_{1}\) and \(\widetilde{\mu}_{2}=\hat{\mu}_{2}\)

Under the above assumptions the optimization problem is transformed as follows:
(13) \(\quad\) minimize \(Q=-\ln |\tilde{\Sigma}|+\operatorname{tr}\left(\tilde{\Sigma}^{-1}\right)\)
subject to:
(14)
(15)
\[
\begin{aligned}
& x_{i}^{\mathrm{T}} W i w_{0}, \text { if OS assigns } x_{i} \text { into } g_{1}, \\
& x_{i}^{\mathrm{T}} \mathrm{~W}<w_{0}, \text { if OS assigns } x_{i} \text { into } g_{2} \\
& w=\widetilde{\Sigma}^{1}\left(\hat{\mu}_{1}-\hat{\mu}_{2}\right),
\end{aligned}
\]
\[
w_{0}={\underset{2}{1}}_{1}^{1}\left(\hat{\mu}_{1}+\hat{\mu}_{2}\right)^{\mathrm{T}} W+\ln \left(\begin{array}{c}
q_{1}  \tag{16}\\
1_{1} \\
q_{1}
\end{array}\right) .
\]

We will consider two assumptions about the covariance matrix.
IV.2. \(\tilde{\Sigma}=\Lambda \hat{\Sigma} \Lambda\) where \(\Lambda=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}\right), \lambda_{i}>0 \forall i=1, \ldots, k\).

In this case we have \(k\) unknown parameters.
Let \(\hat{\Sigma}=\left\|c_{i j}\right\|_{i, j=1}^{k}\) and the inverse matrix to exist and \(\hat{\Sigma}^{-1}=\left\|r_{i j}\right\|_{i, j=1}^{k}\).
Then obviously:
\[
\begin{gathered}
\Lambda^{-1}=\operatorname{diag}\left(\lambda_{1}^{-1}, \lambda_{2}^{-1}, \ldots, \lambda_{k}^{-1}\right),|\Lambda|=\lambda \lambda_{2} \ldots \lambda_{k^{\prime}}\left|\Lambda^{-1}\right|=\lambda_{1}^{-1} \lambda_{2}^{-1} \ldots \lambda_{k}^{-1} \\
|\tilde{\Sigma}|=|\Lambda||\hat{\Sigma}||\Lambda|=\left(\lambda \lambda_{2} \ldots \lambda_{k}\right)^{2}|\hat{\Sigma}| \text { and } \ln (|\tilde{\Sigma}|)=2 \ln \left(\lambda_{1} \lambda_{2} \ldots \lambda_{k}\right)+\ln (|\hat{\Sigma}|) \\
\tilde{\Sigma}=\Lambda \hat{\Sigma} \Lambda=\left\|\lambda_{i} \lambda_{j} c_{i j}\right\|_{i, j=1}^{k} \text { and } \tilde{\Sigma}^{-1}=(\Lambda \hat{\Sigma} \Lambda)^{-1}=\Lambda^{-1} \hat{\Sigma}^{-1} \Lambda^{-1}=\| \begin{array}{|l}
\left|C_{i j}\right|_{i j}\left\|_{i}\right\|_{i, j=1}^{k} \\
\operatorname{tr}\left(\tilde{\Sigma}^{-1}\right)=\operatorname{tr}\left(\Lambda \hat{\Sigma} \Lambda \hat{\Sigma}^{-1}\right)=\sum_{i=1}^{k} \sum_{j=i}^{k} a_{i j} \lambda_{i} \lambda_{j} .
\end{array} .
\end{gathered}
\]

Let us denote the components of the \(k\)-dimensional vectors as follows:
\(\hat{\mu}_{1}=\left(\hat{\mu}_{11}, \hat{\mu}_{12}, \ldots, \hat{\mu}_{1 k}\right)^{T}, \hat{\mu}_{1}=\left(\hat{\mu}_{21}, \hat{\mu}_{22}, \ldots, \hat{\mu}_{2 k}\right)^{T}, w=\left(w_{1}, w_{2}, \ldots, w_{k}\right)^{T}\).
Then the optimization problem is transformed as follows:

\section*{Formulation I.}
\[
\begin{equation*}
\text { Minimize } Q=-\ln (|\tilde{\Sigma}|)+\operatorname{tr}\left(\tilde{\Sigma}^{-1}\right)=-2 \ln \left(\lambda_{1} \lambda_{2} \ldots \lambda_{k}\right)+\sum_{i=1}^{k}{ }_{j=i}^{k} a_{i j} \lambda_{i} \lambda_{j} . \tag{17}
\end{equation*}
\]
subject to:
\[
w_{0}={ }_{2}^{1}\left(\begin{array}{l}
1  \tag{20}\\
1
\end{array}\left(\hat{\mu}_{1}+\hat{\mu}_{2}\right)^{\mathrm{T}} W+\ln \left(\begin{array}{l}
q_{1} \\
l_{1} \\
q_{1}
\end{array}\right) .\right.
\]
\[
\begin{aligned}
& \lambda_{i} \text { i } 1-\varepsilon \\
& \lambda_{i} \text { I } 1-\varepsilon
\end{aligned} \quad i=1, \ldots, k \text { ( } 2 k \text { linear constrains) },
\]
where \(\varepsilon>0, q_{1}, q_{2}, r_{i j^{\prime}} a_{i j^{\prime}} \hat{\mu}_{1 j^{\prime}} \hat{\mu}_{2 j}(i, j=1, \ldots, k)\) are real constants.
We include the \(2 k\) linear constrains (21) since we would like the covariance matrix \(\tilde{\Sigma}\) to be close ( \(\varepsilon>0\) is a small real number) to the maximum-likelihood estimation of the covariance matrix \(\widetilde{\Sigma}\) (17) is a non-linear function in respect to the unknown \(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}\). (18), (20), (21) are \(n+2 k+1\) linear constrains and (19) is a system of \(k\) fractional non-linear equations. Therefore the optimization problem (17)-(21) is a problem of fractional non-linear optimization and could be solved by conventional software packages.

As a result of the proposed nonparametric estimation of the covariance matrix \(\left(\tilde{\Sigma}=\Lambda \hat{\Sigma} \Lambda\right.\) where \(\left.\Lambda=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}\right), \lambda_{i}>0 \forall i=1, \ldots, k\right)\) and the optimization task (17)-(21) we found two multivariate nomal distributions \(\boldsymbol{N}\left(\hat{\mu}_{i}, \widetilde{\Sigma}, i=1, \ldots, 2\right.\) ( \(\hat{\mu}_{i}\) are the maximm-likelihood estimations of the group means), that in accordance with the Bayes discriminant rule will allocate one doservation to the group with greatest posterior probability and this allocation will ooincide with the allocation of the conventional MIP-formulation of the linear classifier's construction (1)- (2) .
IV.3. \(\tilde{\Sigma}=\lambda \hat{\Sigma}_{1}+(1-\lambda) \hat{\Sigma}_{2}\) where \(\lambda \in(0,1)\) and \(\hat{\Sigma}_{1}\left(\hat{\Sigma}_{2}\right)\) is the maximum-likelihood estimation of the first (second) group. In this case we have one unknown parameter.

Let \(\hat{\Sigma}_{1}=\left\|C_{i j}^{(1)}\right\|_{i, j}^{k}\), and \(\hat{\Sigma}_{2}=\left\|C_{i j}^{(2)}\right\|_{i, j=1}^{k}\).
Then obviously:
\(|\tilde{\Sigma}|=\operatorname{det}_{k}(\lambda)\) is a \(k\) degree polynomial of \(\lambda\),

where \(R_{i, j}{ }^{k}(\lambda)-k\) degree polynomial of \(\lambda\),
\(\operatorname{tr}\left({\widetilde{\Sigma} \hat{\Sigma}^{-1}}^{\prime}=\operatorname{tr}\left(\lambda \hat{\Sigma}_{1}+(1-\lambda) \hat{\Sigma}_{2} \hat{\Sigma}^{-1}\right)=\lambda \operatorname{tr}\left(\hat{\Sigma}_{1}-\hat{\Sigma}_{2} \hat{\Sigma}^{-1}\right)+\operatorname{tr}\left(\hat{\Sigma}_{2} \hat{\Sigma}^{-1}\right)\right.\) - linear function of \(\lambda\).
Then the optimization problem is transformed as follows.

\section*{Formulation II.}
(22) \(\quad\) minimize \(Q=-\ln (|\tilde{\Sigma}|)+\operatorname{tr}\left(\tilde{\bar{\Sigma}}^{-1}\right)=-\ln \left[\operatorname{det}_{k}(\lambda)\right]+\lambda \operatorname{tr}\left(\hat{\Sigma}_{1}-\hat{\Sigma}_{2} \hat{\Sigma}^{-1}\right)\)
subject to: \(x_{i}^{\mathrm{T}} \mathrm{W}<\mathrm{w}_{0}\), if OS assigns \(x_{1}\) into \(g_{2}\),
(24)
\[
\left.W_{i}=\underset{11}{1} \sum_{\left.\right|_{i}}^{1} R_{k}^{k} R_{j}^{k}(\lambda)()_{j=1}^{k}\right)\left(\hat{\mu}_{1 j}-\hat{\mu}_{1 j}\right), i=1, \ldots, k \text { ( } k \text { fractional non-linear equations), }
\]
\[
w_{0}={ }_{2}^{1} \begin{aligned}
& 1 \\
& 1
\end{aligned}\left(\hat{\mu}_{1}+\hat{\mu}_{2}\right)^{\mathrm{T}} w+\ln \left(\begin{array}{l}
q_{1} \\
1 \\
q_{1}
\end{array}\right),
\]
where the only variable \(\lambda \in(0,1)\).
The object (criterion) (22) is a non-linear function in respect to the unknown \(\lambda\). (23), (25) are \(n+1\) linear constrains and (24) is a system of \(k\) fractional non-linear
equations. Therefore the optimization problem (22) - (25) is a problem of fractional non-linear optimization and could be solved by conventional software packages.

As a result of the proposed nonparametric estimation of the covariance matrix \(\left(\widetilde{\Sigma}=\lambda \hat{\Sigma}_{1}+(1-\lambda) \hat{\Sigma}_{2}\right.\) where \(\left.\lambda \in(0,1)\right)\) and the optimization task (22)-(25) we find two multivariate normal distributions \(\boldsymbol{N}\left(\hat{\mu}_{i}, \tilde{\Sigma}, i=1,2\right.\) ( \(\hat{\mu}_{i}\) are the maximum-likelihood estimations of the group means), that in accordance with the Bayes discriminant rule will allocate one doservation to the group with greatest posterior probability and this allocation will coincide with the allocation of the conventional MIP-formulation of the linear classifier's construction (1)-(2) .

In fact maybe the true (from statistical point of view) assumption should be not \(\tilde{\Sigma}=\lambda \hat{\Sigma}_{1}+(1-\lambda) \hat{\Sigma}_{2}\) where \(\lambda \in(0,1)\). The true assumption [29, p. 106] has to be
and \(\hat{\Sigma}_{1}\left(\hat{\Sigma}_{2}\right)\) is the maximum-likelihood estimation of the first (second) group) - in this case we have one unknown parameter.

Let \(\hat{\Sigma}_{1}=\left\|C_{i j}^{(1)}\right\|_{i, j=1}^{k}\) and \(\hat{\Sigma}_{2}=\left\|C_{i j}^{(2)}\right\|_{i, j=1}^{k}\).
Then obviously:
\[
\begin{aligned}
& \tilde{\Sigma}^{-1}=\binom{\lambda n_{1} \hat{\Sigma}_{1}+(1-\lambda) n_{2} \hat{\sum}_{2}}{\lambda n_{1}+(1-\lambda) n_{2}}=\left[\lambda n_{1}+(1-\lambda) n_{2}\right]\left\|\left(n_{1} c_{i j}^{1}-c_{i j}^{2}\right) \lambda+n_{1} c_{i j}^{2}\right\|_{i, j=1}^{k}{ }^{k}=
\end{aligned}
\]

Then the optimization problem is transformed as follows:

\section*{Formulation IIa:}

Is the same as (22)-(25) substituting corresponding estimates.

\section*{V. Recursive quadratic programming formulation (Formulation III)}

Our aim here is to create a formulation with quadratic object, all constrains of which being linear. Let us consider again the equation (12)
\[
w_{0}={\underset{2}{1}}_{1}^{1}\left(\tilde{\mu}_{1}+\tilde{\mu}_{2}\right)^{t} w+\ln \left(\begin{array}{c}
q_{2} \\
1 \\
q_{1} \\
q_{1}
\end{array}\right),
\]

Let us assume that \(\tilde{\mu}_{1}+\tilde{\mu}_{2}=\hat{\mu}_{1}+\hat{\mu}_{2}\).
Then (12) is transformed into the following linear constrain:
\[
W_{0}={\underset{2}{1}}_{1}^{1}\left(\hat{\mu}_{1}+\hat{\mu}_{2}\right)^{t} W+\ln \left(\begin{array}{c}
q_{2} \\
1 \\
1 \\
q_{1}
\end{array}\right) .
\]

Step 0. Let \(\widetilde{\mu}_{i}(0)=\hat{\mu}_{i}, i=1,2\).
Step 1. Calculate the covariance matrix \(\tilde{\Sigma}(1)\) of the training sample with means \(\widetilde{\mu}_{i}=\widetilde{\mu}_{i}(0)=\hat{\mu}_{i}, i=1,2\), using the conventional maximum-likelihood estimation:

Under the above assumptions the optimization problem (9) - (12) is transformed as follows:
(27) minimize \(Q(\) step 1\()=\sum_{i=1}^{2} n_{i} D\left(N\left(\tilde{\mu}_{i}, \tilde{\Sigma}(1) \| N\left(\hat{\mu}_{i}, \hat{\Sigma}\right)\right)=\sum_{i=1}^{2} n_{i} D\left(N\left(\tilde{\mu}_{i}, \hat{\Sigma} \| N\left(\hat{\mu}_{i}, \hat{\Sigma}\right)\right)=\right.\right.\)
\[
=n_{1}\left(\tilde{\mu}_{1}-\hat{\mu}_{1}\right)^{t} \hat{\Sigma}^{-1}\left(\tilde{\mu}_{1}-\hat{\mu}_{1}\right)+n_{2}\left(\widetilde{\mu}_{2}-\hat{\mu}_{2}\right)^{\mathrm{T}} \hat{\Sigma}^{-1}\left(\tilde{\mu}_{2}-\hat{\mu}_{2}\right)
\]
subject to
\[
\begin{equation*}
x_{i}^{\mathrm{T}} \mathrm{w} \text { i } w_{0} \text { if } O S \text { assigns } x_{i} \text { into } g_{1}, \tag{28}
\end{equation*}
\]
\[
x_{i}^{\mathrm{T}} W<W_{0} \text { if } O S \text { assigns } x_{i} \text { into } g_{2},
\]
\[
w=\hat{\Sigma}^{-1}\left(\widetilde{\mu}_{1}-\tilde{\mu}_{2}\right),
\]
\[
w_{0}={ }_{2}^{1}\left(\begin{array}{l}
1 \\
1
\end{array}\left(\hat{\mu}_{1}+\hat{\mu}_{2}\right)^{\mathrm{T}} W+\ln \left(\begin{array}{l}
q_{1}^{q} \\
1 \\
q_{1}
\end{array}\right),\right.
\]
\[
\begin{equation*}
\tilde{\mu}_{1}+\tilde{\mu}_{2}=\hat{\mu}_{1}+\hat{\mu}_{2}, \tag{31}
\end{equation*}
\]
where \(w_{0}\) and the components of \(w, \widetilde{\mu}_{1}, \widetilde{\mu}_{2}\) are unrestricted; \(q_{1}, q_{2}\) and all elements of \(\hat{\mu}_{1}, \hat{\mu}_{2}\) and \(\hat{\sum}\) are real constants.

The object (criterion) (27) is a quadratic function in respect to the unknown \(\tilde{\mu}_{i j}\) ( \(i=1,2, j=1, \ldots, k\) ), (28) is a system of \(n\) linear inequalities, (29) and (31) are two systems of \(k\) linear equations and (30) is a linear equation. Therefore we have quadratic object (27) and ( \(n+2 k+1\) ) linear constrains (28)-(31), or the described optimization problem is a task of a quadratic mathematical programming.

The result of step 1 is as follows:
(32) \(\quad\left(\widetilde{\mu}_{1}(1), \tilde{\mu}_{2}(1)\right)=\operatorname{argmin} Q(\) step 1\()\), where \(Q_{1}=\min Q(\) step 1\()=\)
\[
=n_{1}\left(\tilde{\mu}_{1}(1)-\hat{\mu}_{1}\right)^{\mathrm{T}} \hat{\Sigma}^{-1}\left(\tilde{\mu}_{1}(1)-\hat{\mu}_{1}\right)+n_{2}\left(\tilde{\mu}_{2}(2)-\hat{\mu}_{2}\right)^{\mathrm{T}} \hat{\Sigma}^{-1}\left(\tilde{\mu}_{2}(2)-\hat{\mu}_{2}\right) .
\]

Step \(s\). Calculate the covariance matrix \(\tilde{\Sigma}(s)\) of the training sample with means \(\widetilde{\mu}_{i}=\widetilde{\mu}_{i}(s-1), i=1,2\), using the conventional maximum-likelihood estimation:
\[
\begin{equation*}
\tilde{\Sigma}(s)=1_{n} \sum_{n-2}^{1} \sum_{i=1}^{2}\left(x_{j}-\tilde{\mu}_{i}(s-1)\right)\left(x_{j}-\tilde{\mu}_{i}(s-1)\right) . \tag{33}
\end{equation*}
\]

Under the above assumptions the optimization problem (9) - (12) is transformed as follows:
(34) \(\quad \operatorname{minimize} Q(\operatorname{step} s)=\sum_{i=1}^{2} n_{i} D\left(N\left(\tilde{\mu}_{i}, \tilde{\Sigma}(s) \| N\left(\hat{\mu}_{i}, \hat{\Sigma}\right)\right)=n \ln |\hat{\Sigma}|-n \ln |\tilde{\Sigma}(s)|+\right.\)
\[
+n \operatorname{tr}\left(\tilde{\Sigma}(s) \hat{\Sigma}^{-1}-1\right)+n_{1}\left(\tilde{\mu}_{1}-\hat{\mu}_{1}\right) t \hat{\Sigma}^{-1}\left(\widetilde{\mu}_{1}-\hat{\mu}_{1}\right)+n_{2}\left(\tilde{\mu}_{2}-\hat{\mu}_{2}\right)^{t} \hat{\Sigma}^{-1}\left(\tilde{\mu}_{2}-\hat{\mu}_{2}\right)
\]

\footnotetext{
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}
subject to
\[
\begin{align*}
& x_{i}^{\mathrm{T}} \mathrm{~W} \text { i } w_{0} \text {, if OS assigns } x_{i} \text { into } g_{1}, \quad i=1, \ldots, n_{r}  \tag{35}\\
& x_{i}^{\mathrm{T}} W<W_{0} \text {, if OS assigns } x_{i} \text { into } g_{2} \text {, } \\
& w=\widetilde{\Sigma}(s)^{-1}\left(\widetilde{\mu}_{1}-\tilde{\mu}_{2}\right),  \tag{36}\\
& w_{0}=\begin{array}{l}
1 \\
1 \\
1
\end{array}\left(\hat{\mu}_{1}+\hat{\mu}_{2}\right)^{\mathrm{T}} \mathrm{w}+\ln \left(\begin{array}{l}
q_{1} \\
1 \\
1 \\
q_{1}
\end{array}\right),  \tag{37}\\
& \tilde{\mu}_{1}+\tilde{\mu}_{2}=\hat{\mu}_{1}+\hat{\mu}_{2} . \tag{38}
\end{align*}
\]

In other words the difference between two consecutive steps is the matrix \(\widetilde{\Sigma}(s)\) which influenœes the object and the \(k\) linear equations (i. e. (44), (51)). Each step is a task of a quadratic mathematical programing - quadratic object and ( \(n+2 k+1\) ) linear constrains.

The result of step \(s\) is as follows:
\[
\begin{align*}
& \left(\widetilde{\mu}_{1}(s), \widetilde{\mu}_{2}(s)\right)=\underset{\widetilde{\mu_{1}}}{\operatorname{argmin}} Q(\text { step } s) \text {, where }  \tag{39}\\
& \tilde{\mu}_{1}, \tilde{\mu}_{2} \\
& Q_{s}=\min Q(\operatorname{step} s)=n \ln |\hat{\Sigma}|-n \ln |\tilde{\Sigma}(s)|+n \operatorname{tr}\left(\widetilde{\Sigma}(s) \hat{\Sigma}^{-1}-1\right)+ \\
& \tilde{\mu}_{1}, \tilde{\mu}_{2} \\
& +n_{1}\left(\widetilde{\mu}_{1}(s)-\hat{\mu}_{1}\right)^{t \hat{\Sigma}^{-1}}\left(\widetilde{\mu}_{1}(s)-\hat{\mu}_{1}\right)+n_{2}\left(\widetilde{\mu}_{2}(s)-\hat{\mu}_{2}\right)^{t} \hat{\Sigma}^{-1}\left(\widetilde{\mu}_{2}(s)-\hat{\mu}_{2}\right) .
\end{align*}
\]

If we prove that
\[
\begin{equation*}
Q_{1} \text { i } Q_{2} \text { i } \ldots \text { i } Q_{s-1} \text { i } Q_{s} \text { i } \ldots \text {, } \tag{40}
\end{equation*}
\]
then the result would be that our recursive procedure converges as follows:
\[
\begin{equation*}
\tilde{\mu}_{i}(s), i=1,2 \xrightarrow{s \rightarrow \infty} \tilde{\mu}_{i}, \text { so that } \tilde{\Sigma}(s) \xrightarrow{s \rightarrow \infty} \tilde{\Sigma} \tag{41}
\end{equation*}
\]
where \(\tilde{\sum}\) is a maximum - likelihood estimation of the covariance matrix in respect to the training sample and \(\tilde{\mu}_{i}(s), i=1,2\).

For now we have no prove about the above statement, although it seems that it would hold in the practice.

As a result of the proposed non-parametric recursive estimation we find two multivariate normal distributions \(\boldsymbol{N}\left(\widetilde{\mu}_{i}, \widetilde{\Sigma}, i=1,2\right.\), that in accordance with the Bayes discriminant rule will allocate one observation to the group with greatest posterior probability and this allocation will coincide with the allocation of the conventional MIP-formulation of the linear classifier's construction (1)-(2) .

Let us have more than one solution optimal from the classification point of view. Then we will decide the respective optimization problem (formulations I, II or III) for each of them and will choose the solution with minimum values of the divergence criterion \(Q\).

\section*{VI. Conclusion}

In this paper we show that any linear classifier could be considered within the Bayes decision theoretic approach framework. We will carry out our consideration about the mixed integer programming based linear classifier sinøe this is the only classifier that directly minimizes the number of misclassification and it is the best classifier if the criterion is the minimum of the training set misclassification error rate. However we would like to stress again that our consideration is valid for any linear classifier.

We consider the two-group mixed integer based classification and show its connection with the Bayes decision theoretic approach. The conventional MIP-formula-
tion of the linear classifier's construction minimizes the overall misclassification error. This is a NP-hard optimization task which result is a set of infinite number of optimal from mathematical point of view solutions that differ in some value(s) of the classification function's parameter (s). All of them assign each training set observation into one and same group. In other words we have a consistent system from \(n\) inequalities ( \(n\) - the number of the training set observations). We assume that the two groups have multivariate normal distribution with common covariance matrix - the class of optimal (Bayes) classification rules in this case is based on the linear discriminant function. Three optimization formulations, based on the minimization of the divergence criterion under given constrains are proposed. Two of the formulations are nonlinear optimization problems, while the last recursive formulation is a task of quadratic mathematical programming (quadratic object and linear constrains). As a result of the proposed non-parametric estimation we find two multivariate nomal distributions that in accordance with the Bayes discriminant rule will allocate one observation to the group with greatest posterior probability and this allocation will coincide with the allocation of the conventional MIP-formulation of the linear classifier's construation.

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Математическое программирование с точки зрения Байесовской теории принятия решений в случае классификации двух классов

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Статья относится к области методов классификации, известной как дискриминантный анализ. Авторами сделана попытка показать, что "нетрадиционные методы", такие как метод смешанного целочисленного программирования, мопут быть приведены к традищионной Байесовской постановке при известных предположениях о статистико-вероятностной структуре задачи. Вводится определение различных оптимальных решающих функции, основывающеся на виде ошибок. Выводится критерий минимизации и описьвается соответствующая итерационная процедура.```

